EARLY ATTEMPTS AT MECHANISED FELLING/DELIMBING IN NEW ZEALAND

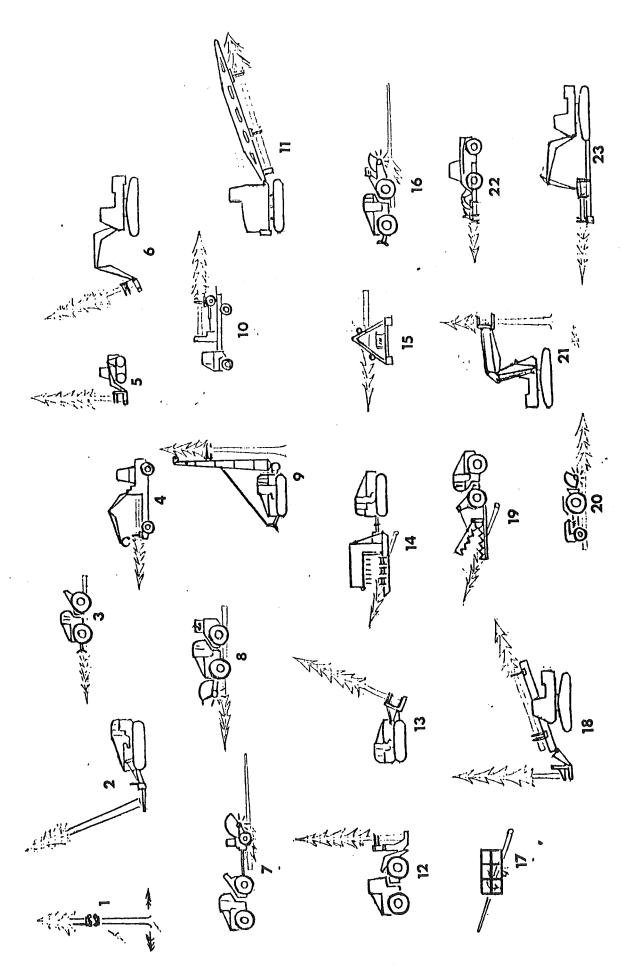
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Over the past 15 years there have been many dreams, attempts and applications of mechanised felling and/or delimbing in New Zealand. Initial attempts to mechanise these operations started during the early 1970's and applications plus interest peaked in the late 1970's. However today in the mid 1980's there are but a very small number of active mechanised felling/delimbing operations in New Zealand.

The brief for this paper is specifically to cover the N.Z. mechanisation activities of the 1970's, and reflect on the variations tested, features/problems encountered, and leads worth pursuing.

MECHANISATION ACTIVITY DURING THE 1970'S

In searching through the LIRA information system, reference was found to some 20 arrangements aimed at mechanised felling/delimbing during the 1970's. A further small number have arisen in the 1980-85 period. The 1970's was thus a particularly active period with interest plus trials and applications widespread. The following figure 1, and subsequent table, illustrate and describe the arrangements identified. Some of these never got past the concepted stage, but many had two or more similar units operating productively.



SKETCH NO.	APPROX. DATE	BRIEF DESCRIPTION	EXTENT OF USE	COMMENTS
	1970	Tree Climbing Chainsaw	Brief trials only	Low tree rate Climbing height problems Cumbersome to move between trees
8	1973–78	Tractor Mounted Felling Shear	$3 \times \mathbb{QM}$ shears and $1 \times \mathbb{R}$ canoke shear used productively by KLC and contractors	Limited directional control, but successful in large diameter radiata
М	1973	Skidder Blade Delimbing	Contractor trials only - various	Inadequate standard of delimbing
4	1974–78	Cancar Processors	2 units used by KLC productively	Good trim and output rate. Hydraulic maintenance problems. Difficulties keeping wood supply up.
ıń	1976-77	Bobcat Fellerbuncher	<pre>l unit extensively trialed and used by contractor productively .</pre>	Very compact and manoeuvrable. Traction problem in loose scoria. Uncomfortable operator ride. Worked in radiata thinning.
9	1976–86	Excavator Based Fellerbunchers	<pre>1 x Drott and approx. 4 x Hitachi units used productively by Panpac contractors</pre>	Good operator comfort and very productive in all weather. Difficulty in following operations keeping up with production.
7	1976–77	Towed Chain Flail Delimber	l unit used productively by contractor Cochrane	High rate of trim. Fixed operating height and problems with dirt hammered into stems.
80	. 1976–79	Front Mounted Chain Flail on Skidder	l unit used produtively by Panpacs	High rate of trim. Adjustable operating height. Chain wear problem.
6	1977	Bolstad Prototype Delimber	Prototype built and briefly trailed	Low cost and ingeniously operated. Fixed trim/prune height. Difficult to alight with trees on sloping ground or if leaning.

COMMENTS	No tree loading provision or slash removal system.	Aimed at performing cancar processor functions but without hydraulics.	Very low stumps and minimum butt splitting due to shear design. Good performance rate and mobility.	Low cost, utilising common logging machine. Good tree control.	Overcomes problem of hammering dirt into stems.	Tested on radiata thinnings.	Adjustable operating height. Unimpaired forward visibility. Used for partial trim only with chainsaw finish.	Low cost. Don't perform well with N.Z. branching habitat.	First local harvester proposal to combine felling and delimbing	Low cost concept for multistem delimbing. Reasonable trim standard.
EXTENT OF USE	Prototype partially built but not completed	Preliminary concept drawing only, by KLC	l unit trialed and used by contractor productively	Approx. 2 or 3 units locally built and used productively by contractors	l unit used productively by contractor Cochrane	Prototype partially built and partially tested	l unit used productively by contractor Paewai	Approx 2 units built for brief trials. Panpac and FRI.	Design drawings by Cable Price, but not built	Built and used productively for short period by contractor Keremete
BRIEF DESCRIPTION	Pullar Truck-mounted Processor	30RB Crane-mounted Processor	<u>Clark Front-end-loader Based</u> <u>Fellerbuncher</u>	Tractor-mounted Fellerbuncher	Cochrane Stationary Chain Flail Delimber	Winstone Stationary Chain Flail Delimber	Rear-mounted Chain Flail on Skidder	Gate Delimbing Frame	<u>Hitachi Harvester</u>	Jaws Delimber
APPROX. DATE	1977	1977	1977-80	1977-	1978-79	1978	1978–79		1978	1978
SKETCH NO.	10	11	12	13	14	15	16	17	18	19

SKETCH NO.	APPROX. DATE	BRIEF DESCRIPTION	EXTENT OF USE	COMMENTS
20	1979	Agric. Tractor Mounted Chain Flail	Built and tested by contractor O'Connor	Low cost. Not robust enough.
21	1979-80	Waratah Delimber-Feller- Buncher	3 units used productively in East Taupo. Numerous exported to Australia.	Successful performers in radiata thinning. All weather operation. Higher capital investment.
22	1982	Sifer Delimber	l unit in brief trials	Problems with malformed trees. High capacity capability.
23	1982-86	Hunt Delimber	l unit used productively by contractor Hunt	Good trim standard. Low cost attachment. In use on steep country operation.

VARIETY OF APPROACHES CONSIDERED

A fair spectrum of mechanisation alternatives were either thought about, tested or used productively.

Felling was performed with single knife/anvil shears, double acting shears and more recently by chainsaw felling head (Hultdin head on Bell logger). Limited-directional-control felling was widely used (especially on larger butt diameters), as was controlled felling and bunching. Accumulating numerous small diameter stems prior to bunching was also tested. Generally mechanised felling was found to present few problems, the major one possibly being that following operations (of delimbing and extraction) could not keep up with the highly productive felling machines available. Fellerbunchers were found to be ideal in bunching stems for a grapple skidder in a high output operation. They also produced very low stump heights.

Delimbing was achieved using various types of knives and chain flails. The approaches have delimbed standing trees prior to felling, felled trees at the stump, and trees bought to the landing. All have worked satisfactorily and have been suited to specific logging situations. Low quality trimming/high quality trimming has also been tested on various tree species and knowledge gained. The mechanisation of delimbing identified many more problems than those encountered in mechanised felling, the major difficulties being:

- achieving a high output rate to offset costs;
- meeting required mill delimbing standards;
- reliability of equipment involved.

However, chain flails were found to be satisfactory in some operations involving small piece size minor species destined for pulp mills.

Combined felling/delimbing by single machine evolved towards the end of the 1970's with a New Zealand developed machine being locally applied and also exported in numbers.

Further analysis of the variety of mechanisation approaches indicates use on flat country, moderate slopes and even more recently in a very steep country operation (Hunt delimber). Both clearfell and thinning operations have been well explored. The range has involved low capital cost alternatives (gate delimber) through to high capital cost alternatives (cancar processors). All types of base machines (dozer, skidder, agric. tractor, front-end-loaders, excavators, rope cranes, sledges, truck chassis') have been utilised in the mechanisation considerations. Whilst different base machine types suit different situations, possibly the hydraulic excavator base was found to provide the best overall characteristics whether for felling or delimbing or both combined. Excavator base units provide good operator comfort, the best reach capability, good reliability and a capability on sloping terrain.

The industry's investment and effort in mechanisation development

during the 1970's was thus considerable. All sections including contractors, forestry producer companies and equipment suppliers, contributed/participated and this was a good healthy situation. Detailed considerations of mechanisation results were regularly monitored/highlighted by the industry's research and development teams (LIRA and FRI), and much information distributed. Relevant references that summarise this subject include the following earlier LIRA seminar papers:

- "Mechanisation of Smallwood Harvesting in N.Z." by Gordon. Paper presented at Smallwood Harvesting seminar held by LIRA, June 1980.
- "Mechanisation of Felling and Delimbing in New Zealand" by Gleason. Paper presented at Logging Machinery seminar held by LIRA, June 1982.
- 3. "The Future of Smallwood Mechanisation in New Zealand" by Cochrane, Gleason, Lawson, Twaddle. Paper presented at seminar on Research and Development in Tree Harvesting and Transportation held by LIRA, June 1983.

The trends and potential for mechanised felling and delimbing are well identified in these references.

CONCLUDING COMMENTS

Overall, mechanisation of felling/delimbing in New Zealand was given a concerted and positive consideration during the 1970's. Few alternatives were left unexplored. The situation today, with only a very small number of continuing mechanised operations, is I consider an accurate indication of the potential for mechanisation in the created logging environment. This environment in N.Z. is characterised by such factors as extensive industry use of small contractors, controlled operational output, the highly loaded cost of imported technology and traditional conservatism by controlling personnel.

The logging environment however is a changing one, particularly with respect to available equipment/technology, changes in workforce attitude/supply considerations, and economic considerations. For this very reason the industry must continually address and reconsider the place of mechanisation, as is now again being done at this 1986 LIRA seminar.

Mechanisation of felling/delimbing will eventually come, given the right industry conditions. One only has to reflect on history or to look at other industries, whether in N.Z. or abroad. It is possibly the only means of making a significant efficiency advance (output/cost/safety) in this phase of ground based logging.

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